# Lucas Nunes Alegre

 $\square$ +55 51 992754053 |  $\boxtimes$ l<br/>nalegre@inf.ufrgs.br |  $\bigotimes$ lucasalegre.github.i<br/>o |  $\heartsuit$ github.com/LucasAlegre

#### Education

#### **Doctor of Philosophy – Computer Science** Jan. 2021 – Feb. 2025 Universidade Federal do Rio Grande do Sul (UFRGS) and Vrije Universiteit Brussel (VUB) Porto Alegre, Brazil • Supervisors: Prof. Ana L. C. Bazzan and Prof. Bruno C. da Silva (Univ. of Massachusetts) • One-year Doctoral Stay at Vrije Universiteit Brussel (VUB) — Supervisor: Prof. Ann Nowé • Title: Sample-Efficient Multi-Task and Multi-Objective Reinforcement Learning by Combining Multiple Behaviors Bachelor of Science Cum Laude – Computer Science Jan. 2016 – Dec. 2020 Universidade Federal do Rio Grande do Sul (UFRGS) Porto Alegre, Brazil • Supervisor: Prof. Bruno C. da Silva – Cumulative GPA: 4.0/4.0 EXPERIENCE Jan. 2021 – Feb. 2025 **Doctoral Researcher** Institute of Informatics - UFRGS Porto Alegre, Brazil • Advisors: Prof. Ana L. C. Bazzan and Prof. Bruno C. da Silva (Univ. of Massachusetts) **Research Intern** Summer 2024 Disney Research Zürich, Switzerland • Robotics Team led by Moritz Bächer. Designed novel deep RL algorithms for motion tracking on physical characters that can be deployed in real-world robots. **Project Manager** Jan. 2023 - ongoingFarama Foundation Remote • I am the creator and maintainer of MO-Gymnasium, the main library of multi-objective RL environments. The Farama Foundation is a nonprofit organization that maintains the largest open-source RL libraries in the world. **Doctoral Researcher** Aug. 2022 – Aug. 2023 AI-Lab at Vrije Universiteit Brussel (VUB) Brussels, Belgium • Advisor: Prof. Ann Nowé • Introduced the first model-based multi-objective RL algorithm for domains with continuous state spaces. **Research Intern** Winter 2020 Technische Universität Berlin Berlin, Germany • Prof. Kai Nagel's group. Developed a RL traffic signal controller with Fourier basis function approximation that outperformed a state-of-the-art rule-based controller in a real-world multiagent scenario. **Undergraduate Research Assistant** Aug. 2017 – Dec. 2020 Multiagent Systems Lab. (Institute of Informatics - UFRGS) Porto Alegre, Brazil

• Advisors: Prof. Ana L. C. Bazzan and Prof. Bruno C. da Silva

## Selected Publications (Full List on Google Scholar)

NeurIPS 2023	Lucas N. Alegre, Ana L. C. Bazzan, Ann Nowé and Bruno C. da Silva. Multi-Step
	Generalized Policy Improvement by Leveraging Approximate Models. Thirty-seventh
	Conference on Neural Information Processing Systems, 2023.
NeurIPS 2023	Florian Felten <sup>*</sup> , Lucas N. Alegre <sup>*</sup> , Ann Nowé, Ana L. C. Bazzan, El-Ghazali Talbi, Grégoire
	Danoy and Bruno C. da Silva. A Toolkit for Reliable Benchmarking and Research in
	Multi-Objective Reinforcement Learning. Thirty-seventh Conference on Neural
	Information Processing Systems Track on Datasets and Benchmarks, 2023.
AAMAS 2023	Lucas N. Alegre, Diederik M. Roijers, Ann Nowé, Ana L. C. Bazzan and Bruno C. da Silva.
	Sample-Efficient Multi-Objective Learning via Generalized Policy Improvement
	<b>Prioritization</b> . Proceedings of the 22nd International Conference on Autonomous Agents and
	Multiagent Systems, 2023.

- ICML 2022 Lucas N. Alegre, Ana L. C. Bazzan and Bruno C. da Silva. **Optimistic Linear Support and Successor Features as a Basis for Optimal Policy Transfer**. Proceedings of the Thirty-ninth International Conference on Machine Learning, 2022.
- AAMAS 2021 Lucas N. Alegre, Ana L. C. Bazzan and Bruno C. da Silva. Minimum-Delay Adaptation in Non-Stationary Reinforcement Learning via Online High-Confidence Change-Point Detection. Proceedings of the 20th International Conference on Autonomous Agents and Multiagent Systems, 2021.

#### **OPEN SOURCE PROJECTS**

MO-Gymnasium | github.com/Farama-Foundation/MO-Gymnasium | Paper ★+280
 Library of environments for multi-objective reinforcement learning (MORL).

**MORL-Baselines** | github.com/LucasAlegre/morl-baselines |  $\bigstar$ +300

• Library of MORL algorithms implementations.

SUMO-RL | github.com/LucasAlegre/sumo-rl  $\bigstar$ +720

• Open source repository of reinforcement learning environments for traffic signal control.

#### Honors & Awards

- 1/200 selected internationally for the Heidelberg Laureate Forum 2024 and 1/30 selected to receive the Abbe Grant from the Carl Zeiss Foundation
- NeurIPS 2023 Scholar Award
- AAMAS 2023 Student Scholarship
- Best Paper Award LXAI Workshop @ ICML 2021
- Brazilian Computer Society Distinguished Student Award, 2021
- Top Reviewer NeurIPS 2022
- Highlighted Reviewer ICLR 2022
- Graduated cum laude in Computer Science. Cumulative GPA: 4.0/4.0, 2021
- Ph.D. Scholarship from the Brazilian National Council for Scientific and Technological Development (CNPq) and the Brazilian Coordination for the Improvement of Higher Education Personnel (CAPES) (2021–2024)
- Finalist of the City Brain Challenge KDD Cup 2021
- 1st Place at PUCRS University Entrance Exam Computer Science, 2016

### TEACHING

Data Science Specialization Course - Teaching Assistant	Aug. 2023 — Aug. 2024
Institute of Informatics - UFRGS	Porto Alegre, Brazil
Artificial Intelligence - Teaching Assistant	Jan. $2022 - Jul. 2022$
Institute of Informatics - UFRGS	Porto Alegre, Brazil
Fundamentals of Algorithms - Teaching Assistant	Aug. 2021 — Dec. 2021
Institute of Informatics - UFRGS	Porto Alegre, Brazil
Introduction to Algorithms - Monitor	Aug. 2016 — Dec. 2016
Institute of Informatics - UFRGS	Porto Alegre, Brazil

#### INVITED TALKS

**Princeton RL Lab.** Sample-Efficient Multi-Task and Multi-Objective Reinforcement Learning by Combining Multiple Behaviors. 2024.

**Cohere For AI.** Sample-Efficient Multi-Task and Multi-Objective Reinforcement Learning by Combining Multiple Behaviors. 2024. [Talk Link]

University of Luxembourg. Towards Sample-Efficient Multi-Objective Reinforcement Learning. 2023. Vrije Universiteit Brussel. Sample-Efficient Multi-Objective Learning via Generalized Policy Improvement. 2023.

STUDENTS	
Liam Mertens (Bachelor, VUB)	2023
Vicent N. de Almeida (Bachelor, UFRGS)	2022
Program Committee Member/Reviewer	
International Conference on Machine Learning (ICML)	2022 - 2024
Conference on Neural Information Processing Systems (NeurIPS)	2022 - 2024
International Conference on Learning Representations (ICLR)	2022 - 2025
Reinforcement Learning Conference (RLC)	2024
AAAI Conference on Artificial Intelligence	2023 - 2025
International Conference on Autonomous Agents and Multiagent Systems (AAMAS)	2020 - 2023
International Joint Conference on Artificial Intelligence (IJCAI)	2024
Neural Computing and Applications (NCAA)	
IEEE Transactions on Artificial Intelligence	
Workshop Reviewer: ALA (2023–2024), MODeM (2023–2024), EWRL 2023, LXAI@ICML 20	21

Volunteer: AAMAS 2023, AAMAS 2021, LXAI@ICML 2021, NIME 2019.

#### TECHNICAL SKILLS

Languages: Portuguese (Native), English (Fluent), Spanish (Beginner).
Programming Languages: Python, C/C++, Java, R, MATLAB, Kotlin, SQL.
Tools & Others: Jax, PyTorch, Tensorflow, Scikit-Learn, Gym/Gymnasium, Pandas, NumPy, Matplotlib, i-graph, OpenCV, QT, Git, Unix/Linux, Cplex, LATEX, SUMO, Network Analysis, Graphistry, VS Code.